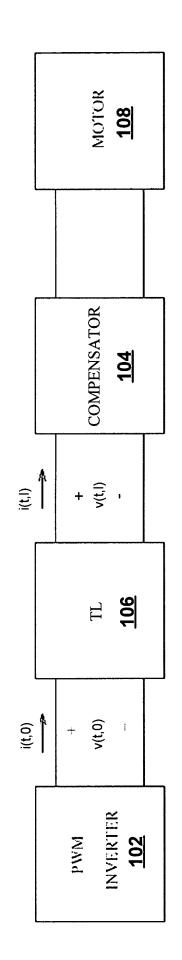
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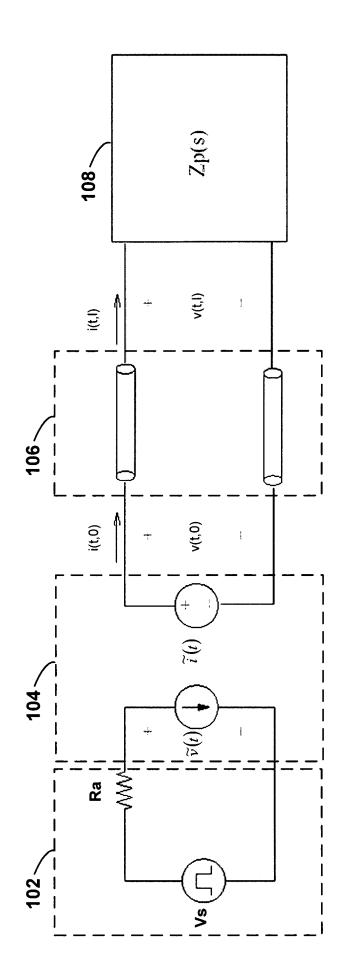
**MOTOR** 108 v(t,I) i(t,) 106  $\equiv$ v(t,0) i(t,0) COMPENS. VIOR 104  $\widetilde{v}(t)$ 1001 INVERTER PWN 102

## **FIGURE 1A**

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**FIGURE 1B** 



**FIGURE 2** 

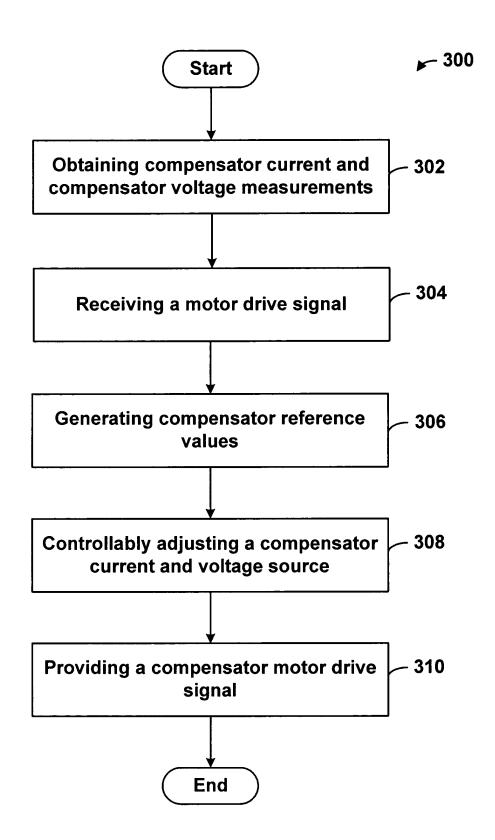
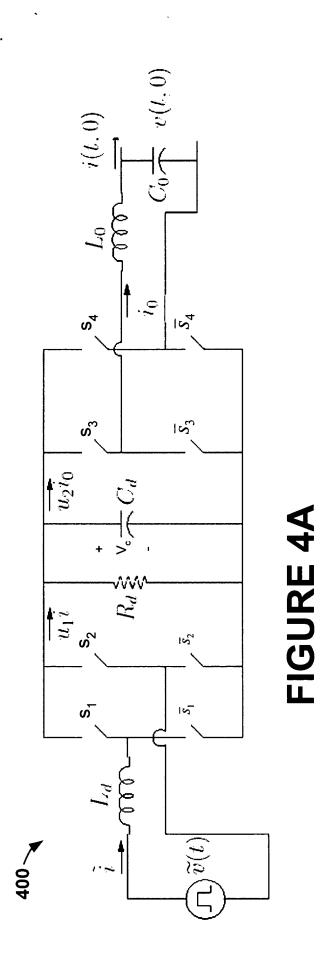
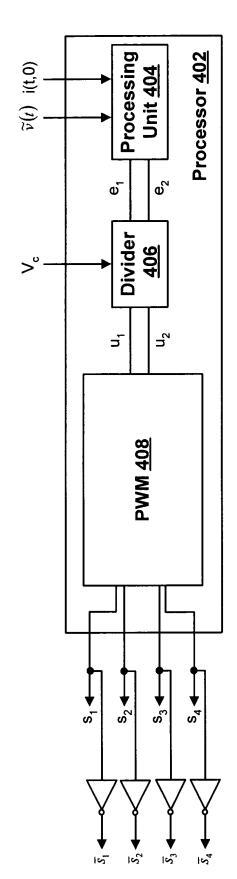


FIGURE 3





**FIGURE 4B** 

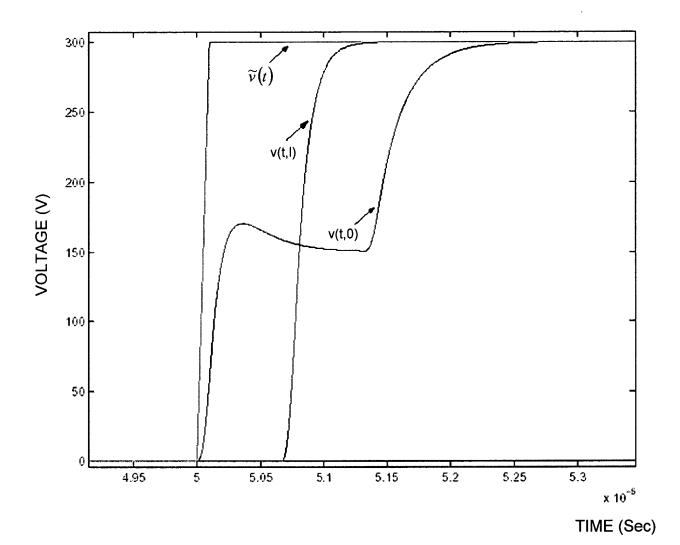
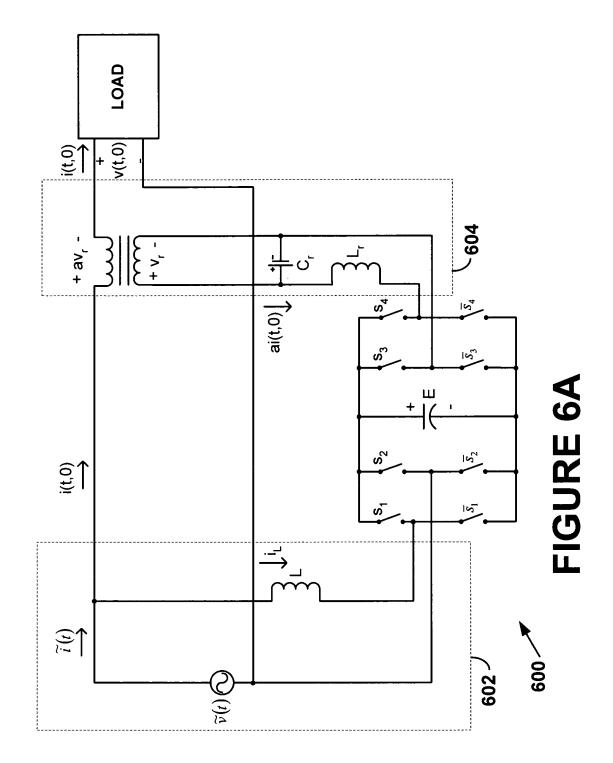
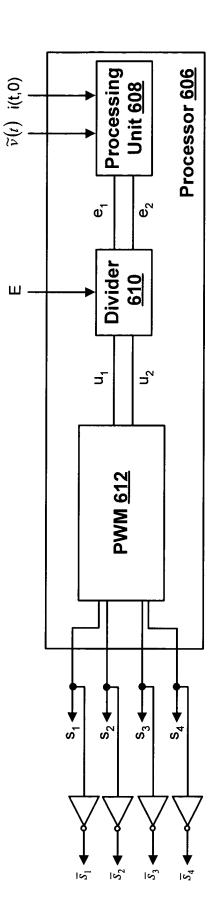


FIGURE 5



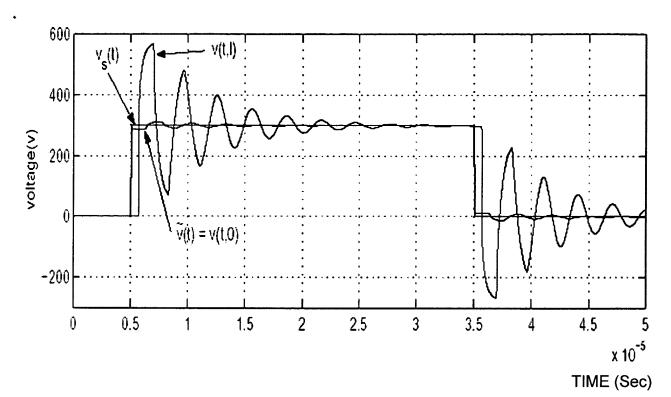
: :

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**FIGURE 6B** 

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## FIGURE 7

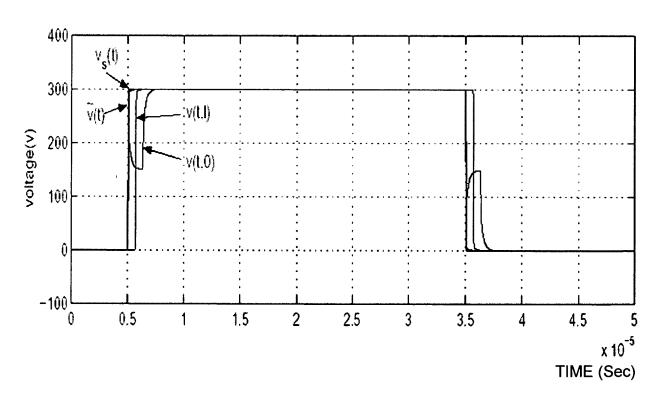
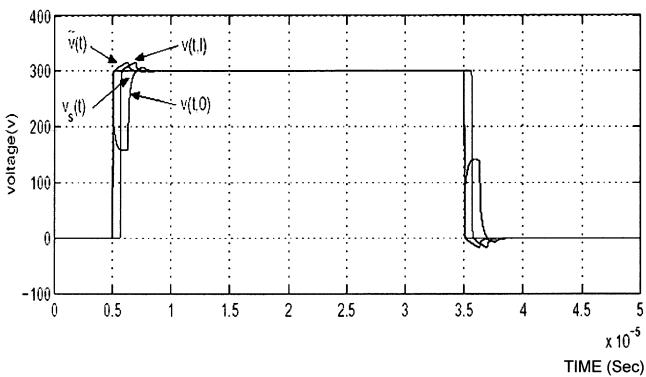


FIGURE 8

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## FIGURE 9

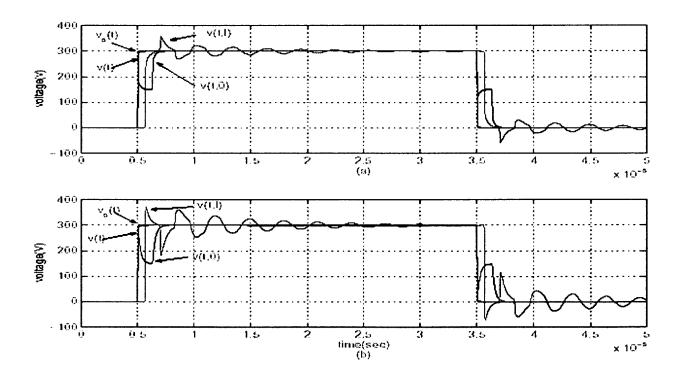
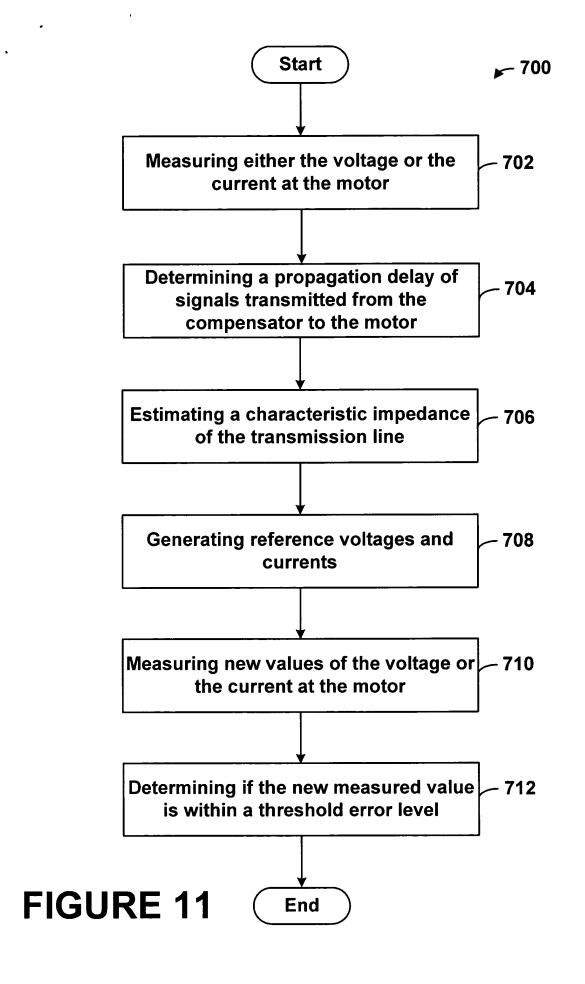


FIGURE 10



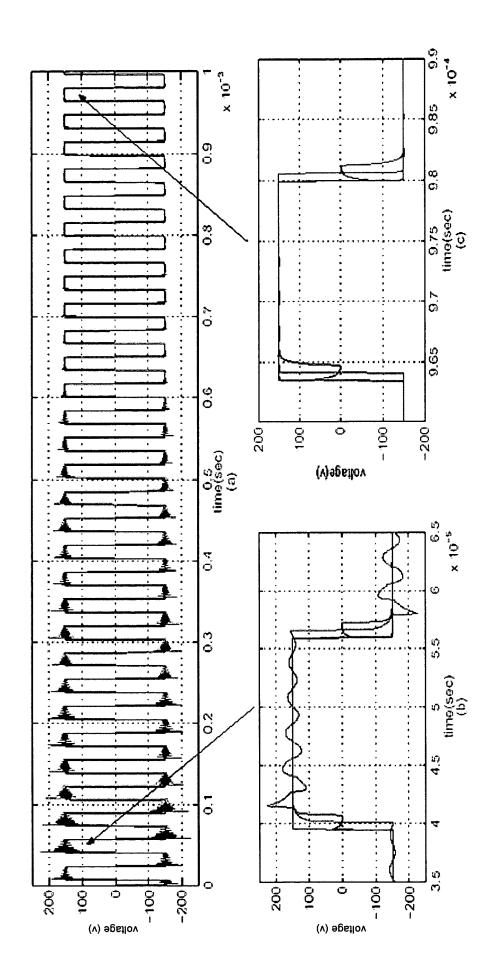


FIGURE 12